# COLLABORATIVE INNOVATION DAY

4<sup>th</sup> October 2022 | Virtual Event

# 5G-Blueprint

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ORGANIZED BY:









# **5G-BLUEPRINT IN A NUTSHELL**





Driven in autonomous mode: 98.2 % of the trajectory\*









Edge & corner cases



5G-Blueprint approach

\* https://www.cs.cmu.edu/~tjochem/nhaa/

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### **5G-BLUEPRINT ULTIMATE GOAL**



5G-Blueprint designs and validates technical architecture, business, and governance model for uninterrupted cross-border teleoperated transport based on 5G connectivity.







# **OBJECTIVES**



# ECHNOLOGICAL

- Design and implement a 5G network for CAM services
- Develop and implement the prototype of a TO system
- Implement and deploy enabling functions guaranteeing safety and increasing value
- Validate the end-to-end TO transport solution supported by 5G in real-life crossborder scenarios

# **SUSINESS**



- 5G TO transport market analysis
- Commercial possibilities
- Positions the possible role of TO transport based on 5G in CAM
- TO transport based on 5G connectivity market adoption

# REGULATORY



- Identify regulatory issues
- Recommended actions

# **USE CASES**



**UC1:** Automated barge control



**UC4:** Remote take over



**UC2:** Automated docking





**Teleoperated crane** 

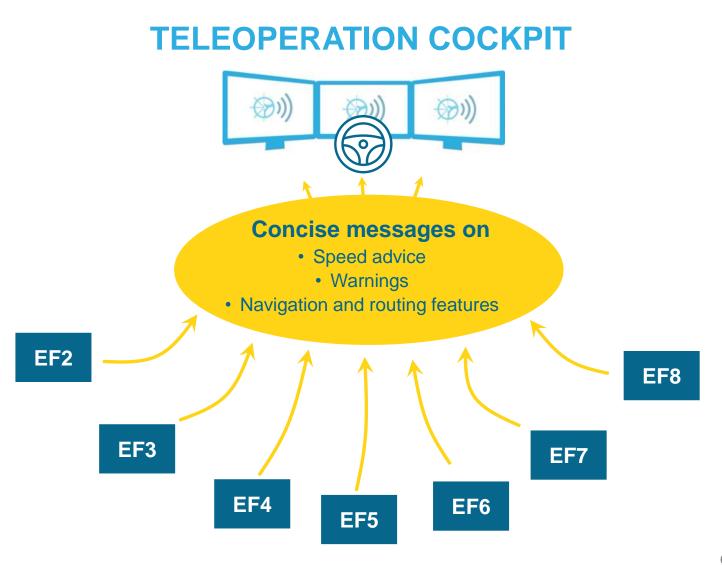
#### **UC3:** CACC-based platooning



# **ENABLING FUNCTIONS**



EF1	Enhanced awareness dashboard
EF2	Vulnerable Road User interaction
EF3	Timeslot reservation at intersections
EF4	Distributed perception
EF5	Active collision avoidance
EF6	Container ID recognition
EF7	ETA sharing
EF8	Scene analytics



# **5G PILOT SITES**



#### **VLISSINGEN**

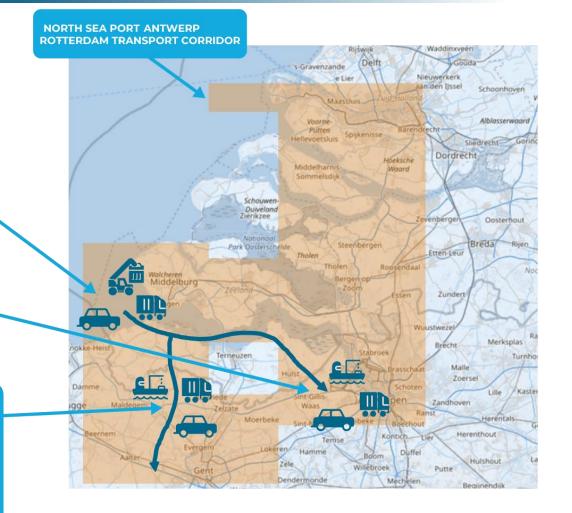
- 5G enhancements for: direct-control teleoperation on roadways, docking, and platooning
- Enabling functions support:
  - Estimated Time of Arrival
  - Timeslot reservation at intersections
  - Container ID recognition
  - Active collision avoidance
  - Enhanced awareness dashboard

#### **ANTWERP**

- 5G enhancements for: direct-control teleoperation on roadways/waterways, and platooning
- Enabling functions support:
  - Estimated Time of Arrival
  - Distributed perception
  - Scene analytics
  - Active collision avoidance
  - Enhanced awareness dashboard

#### **ZELZATE** (cross-border site)

- Seamless roaming
- 5G enhancements for: direct-control teleoperation on roadways/waterways, and platooning
- Enabling functions support:
  - Estimated Time of Arrival
  - Vulnerable Road User interaction
  - Timeslot reservation at intersections
  - Active collision avoidance
  - Enhanced awareness dashboard



# **5G-BLUEPRINT CHALLENGES**



#### **Network requirement**

- Low latency
- High throughput
- High availability
- At cross-borders



#### Safe direct control TO

- Vehicle safety fallback at ASIL
- Security on all levels
- Sufficient situational awareness operator
- Safe operator handover during active ToD session
- Applicability on public road

#### **Autonomous mobility**

- Automated docking
- CACC





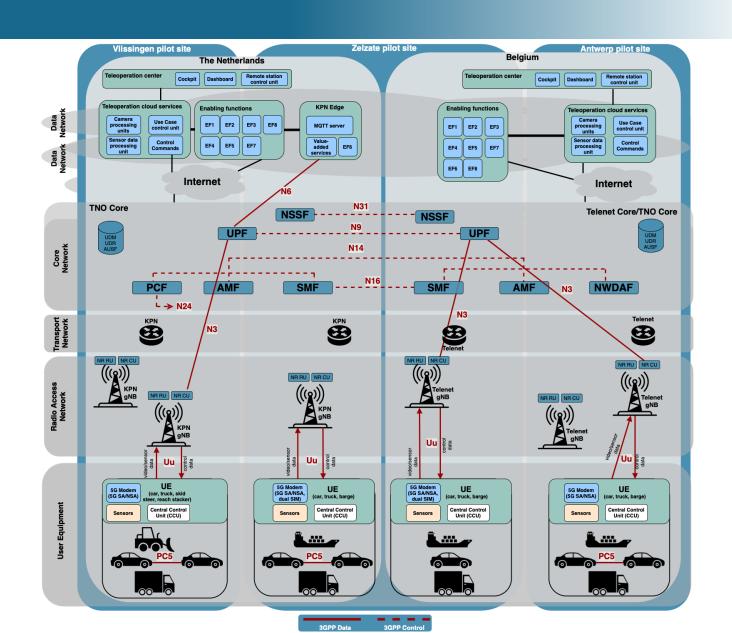
# **5G-BLUEPRINT CHALLENGES**





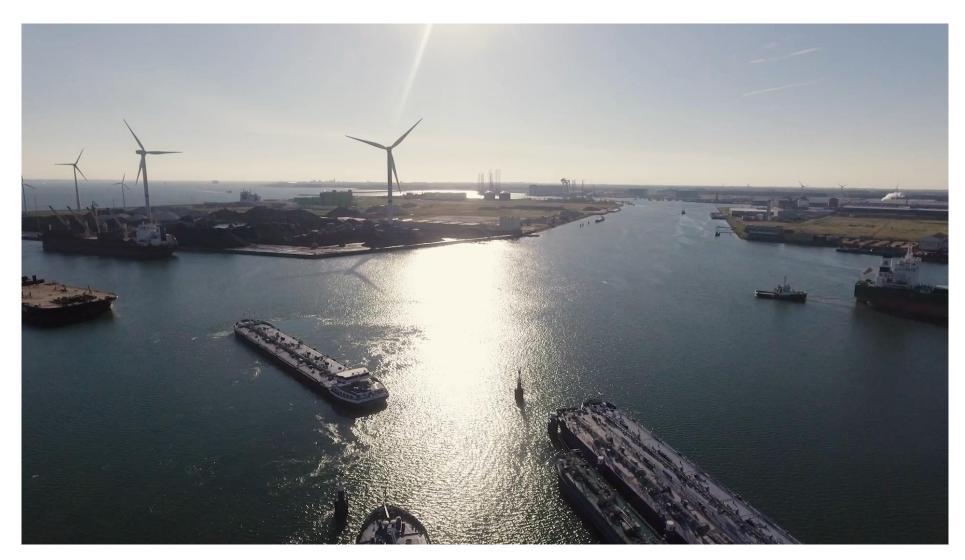
# **NETWORK ARCHITECTURE**





# DEMOS





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# **CONSORTIUM AS A WHOLE**



Network operators







Vehicle OEMs



Teleoperation OEMs







Logistics

**Transport** 

VERBRUGGE INTERNATIONAL E.V.









Software

[sentors]

room 40



Research institutes









Connected Mobility sector



















# **ADVISORY BOARD**











### **FACTS & FIGURES**



**Project Acronym**: 5G-Blueprint

Project Name: Next generation connectivity for enhanced, safe & efficient transport & logistics

Funded Under: H2020-ICT-2018-20

**Topic:** ICT-53-2020: 5G PPP (5G for Connected and

Automated Mobility)

Call for proposal: H2020-ICT-2019-3

**Starting Date**: 01/09/2020

**Duration**: 36 Months

Total cost: EUR 13,9 M

**EU contribution**: EUR 10 M

Project Coordinator: Dr Wim Vandenberghe, Ministerie van Infrastructuur en Waterstaat

Technical Coordinator: Prof. Johann Márquez-Barja, Interuniversitair Micro-Electronica Centrum



# THANK YOU FOR YOUR ATTENTION



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