

# Teleoperation and automation are complementary approaches



Driven in autonomous mode:  
98.2 % of the trajectory\*

27 years of  
R&D later ...



2%  
issue



Edge & corner cases



5G-Blueprint  
approach



## 5G seamless roaming for teleoperated driving 5G-Blueprint approach

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# Outline



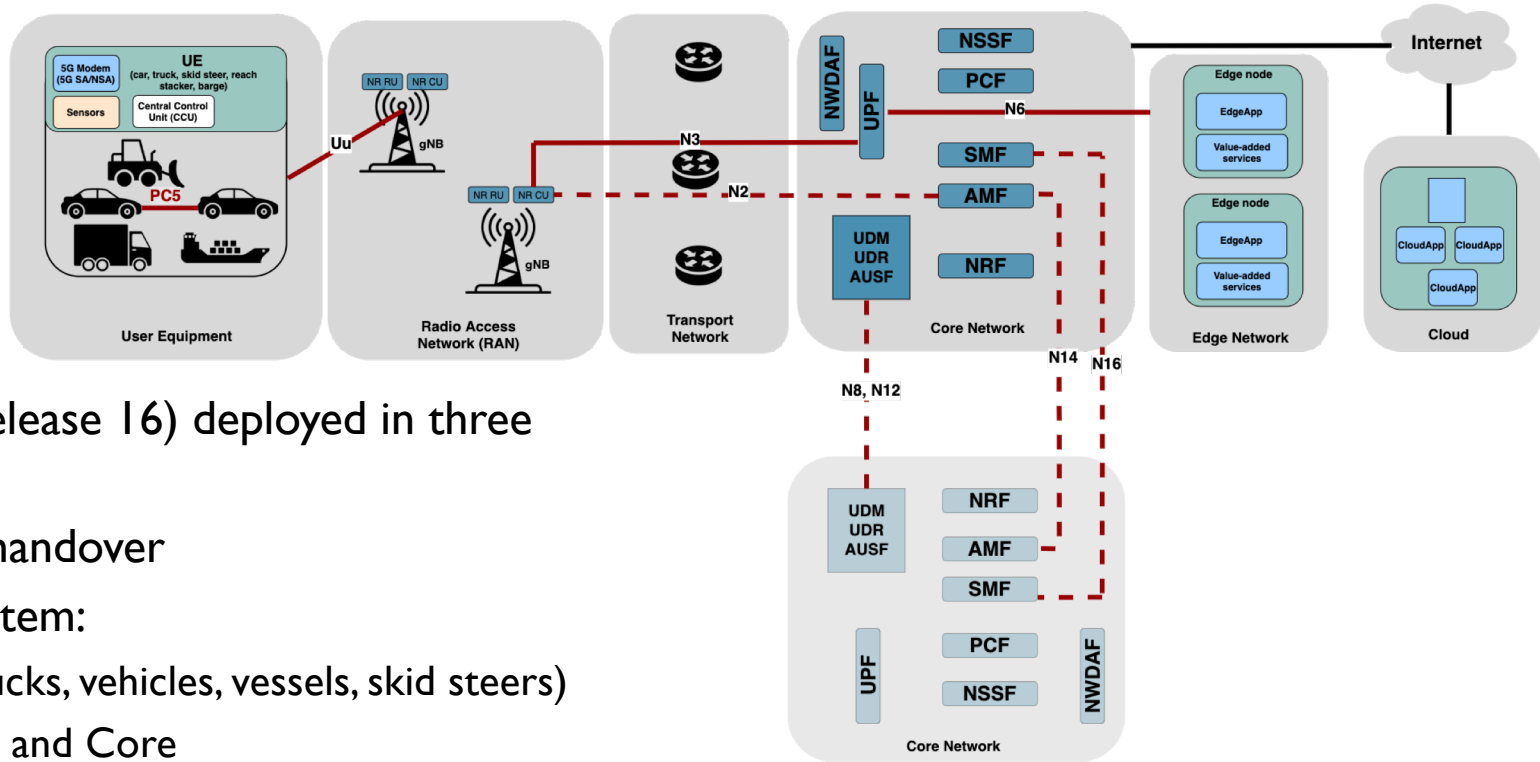
- Quick overview of 5G-Blueprint project
- Automotive use cases and teleoperation
- 5G seamless roaming
- Summary & Lessons learned

# Outline



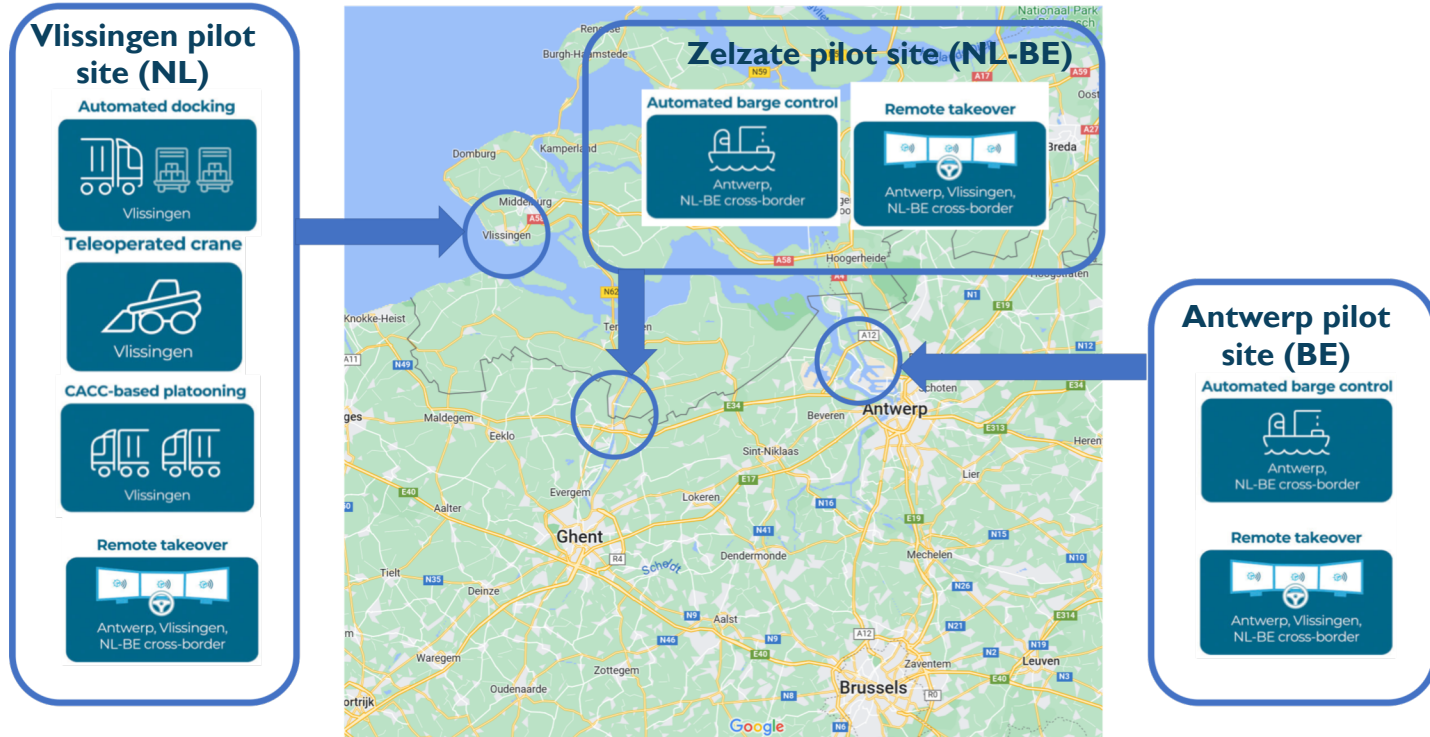
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# 5G-Blueprint combines (cross-border) 5G SA with teleoperated driving and sailing



- 5G SA (Release 16) deployed in three pilot sites
- Seamless handover
- 5G ecosystem:
  - UE (trucks, vehicles, vessels, skid steers)
  - 5G NR and Core
  - Data network (Enabling functions and Use case components)

# Use cases and Pilot sites

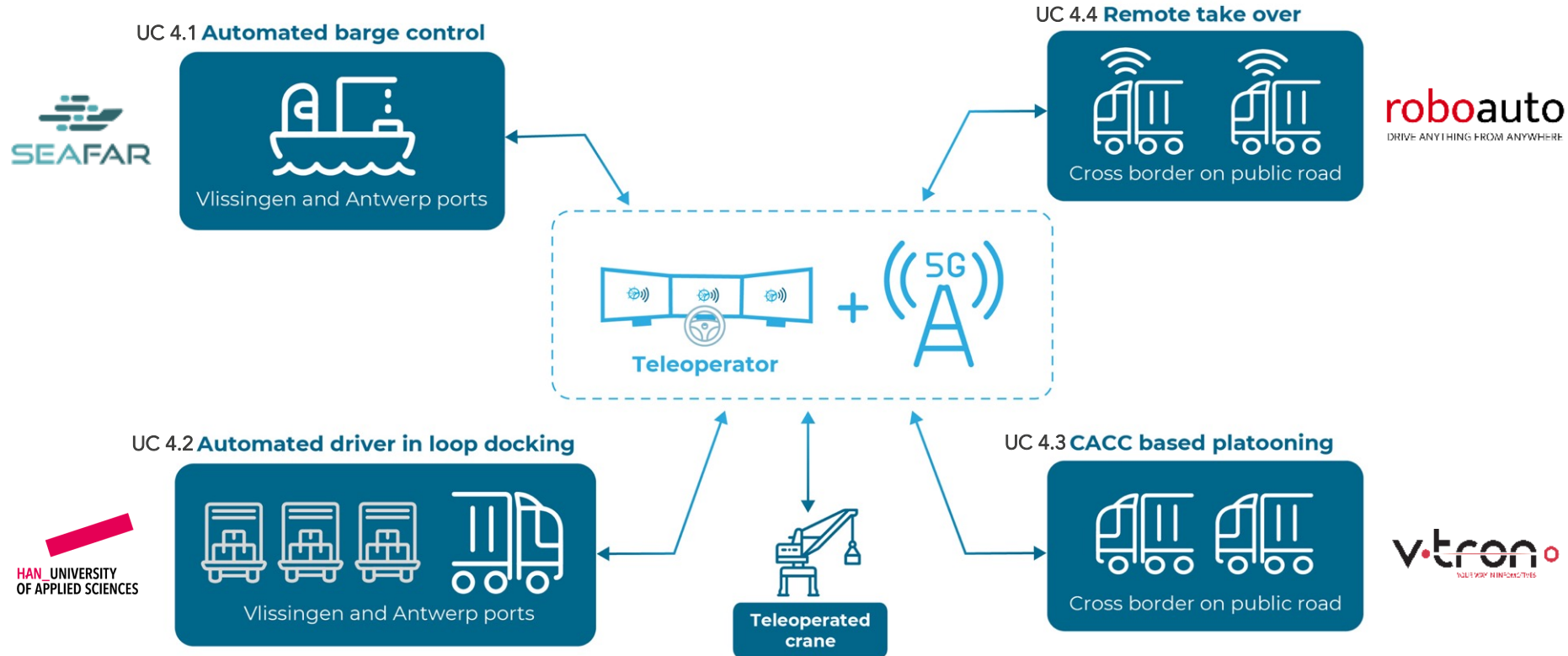


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# Use cases are tested in real-life environments such as busy ports and public roads





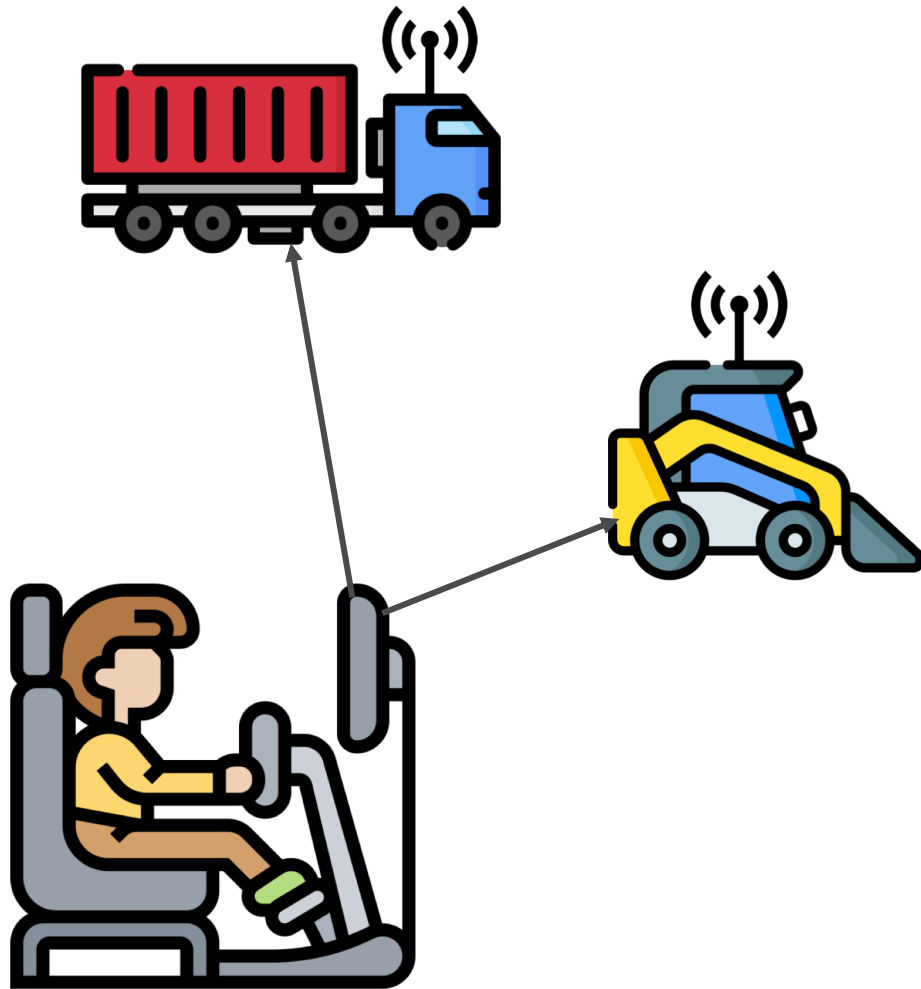
# Challenges

## Trucks

- Increasing driver shortage
- Increase in online shopping
- Waiting times at depots
- Bounded to one vehicle
- Long away from home

## Material handling

- Unsafe operating conditions
- Bounded to one vehicle



# Solution

## TELEOPERATION USING 5G

### EXPECTED BENEFITS:

- Higher efficiency
- Switch between vehicles
- Less waiting
- Attract new type of driver/operator
- Safer work environment
- Bridge to fully autonomous
- Drivers can work from other time zones during the day, while the truck drives at night.
- One operator can manage a platoon of multiple trucks by automating the following trucks
- 'Gamification' of the traditional professions using teleoperation could potentially interest the younger generation.





# Teleoperated Docking scaled from simulations to pilot with trucks



Digital twin /  
Simulations



Scaled  
prototype  
testing



Full scale  
pilots



# Teleoperated Docking scaled from simulations to pilot with trucks



MSP Onions test site in the Netherlands





# Teleoperated Docking scaled from simulations to pilot with trucks

Truck-Trailer combination



Teleoperator view



Cabin



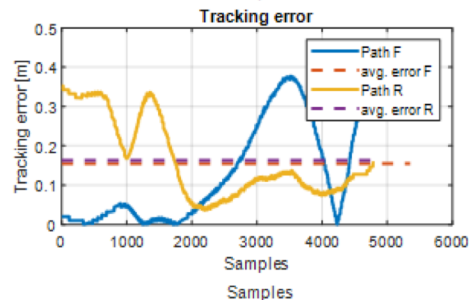
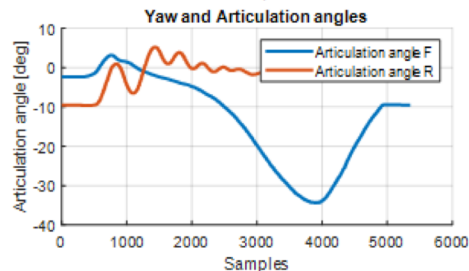
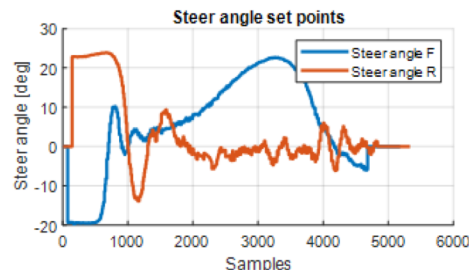
# Average tracking error 0.16m, target values less than 0.5m

An example test run at MSP Onions

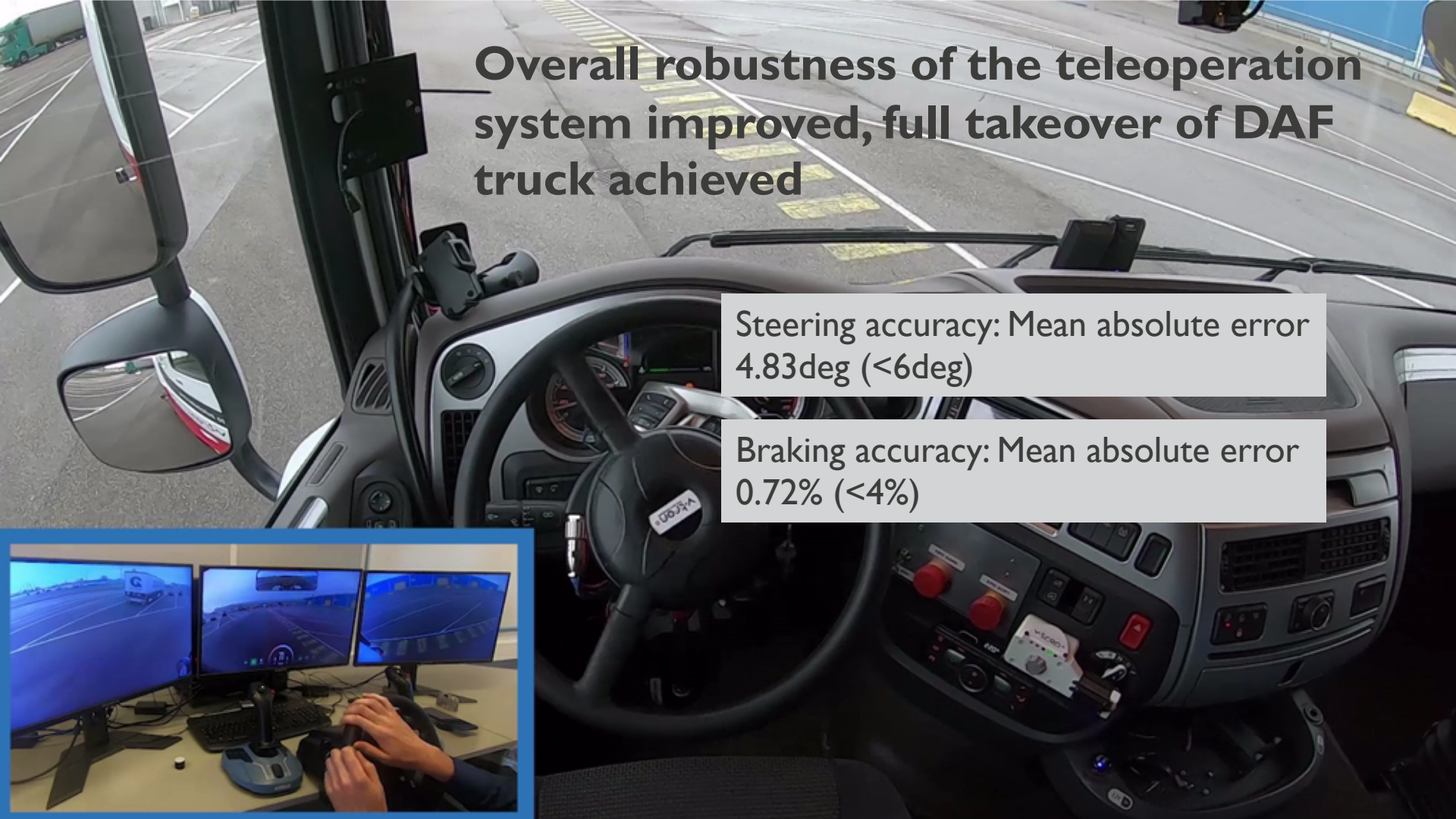


Final docking state error:

- A = 3.6cm, required < 10cm
- B = 8.4cm, required < 10cm
- C = 0.4deg, required < 2deg







**Overall robustness of the teleoperation system improved, full takeover of DAF truck achieved**

Steering accuracy: Mean absolute error 4.83deg (<6deg)

Braking accuracy: Mean absolute error 0.72% (<4%)



Steering accuracy: Mean absolute error  
2.41 deg (<3deg)

Braking accuracy: Mean absolute error  
0.51% (<4%)

**Overall robustness of the teleoperation  
system improved**



# Outline

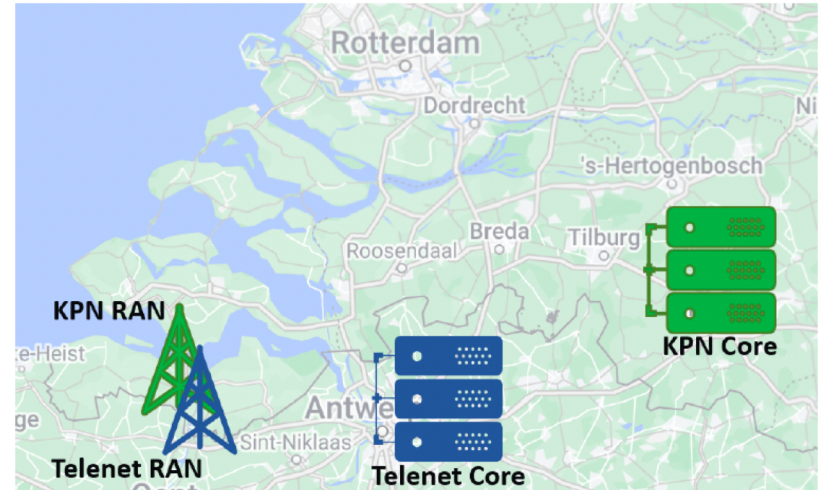
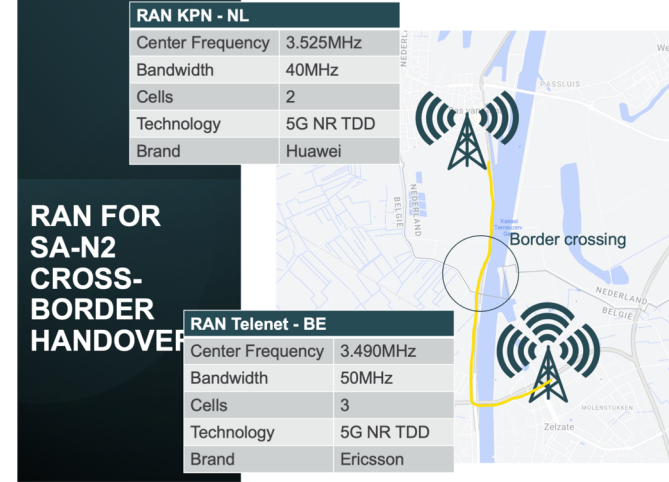
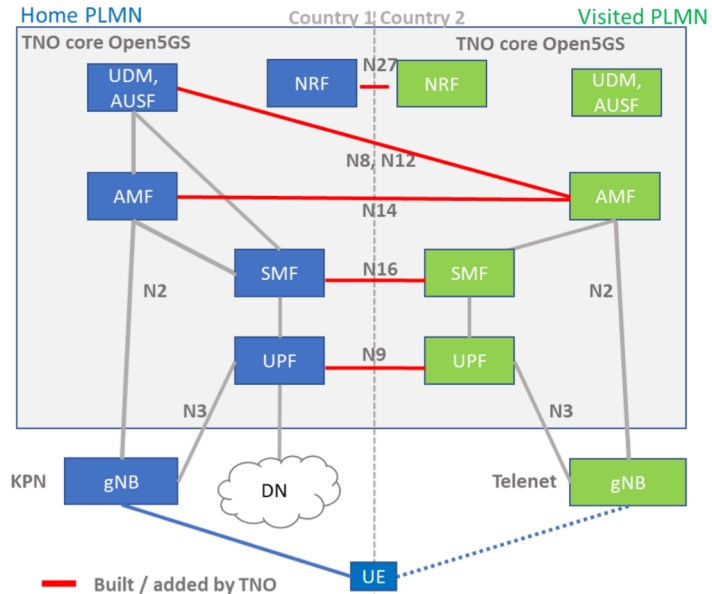


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# Seamless roaming

- 5G SA seamless roaming working and deployed at cross-border site
- Network evaluation done at BE and NL sites
- Successful seamless roaming demos





# Roaming procedures can be optimized by combining Home routed SA principles with N14-based roaming

## N14 vs N2

Seamless cross-border N14 handover performs similar to the N2 handover, the main difference is that it depends on the latency between the cores

## Lab results

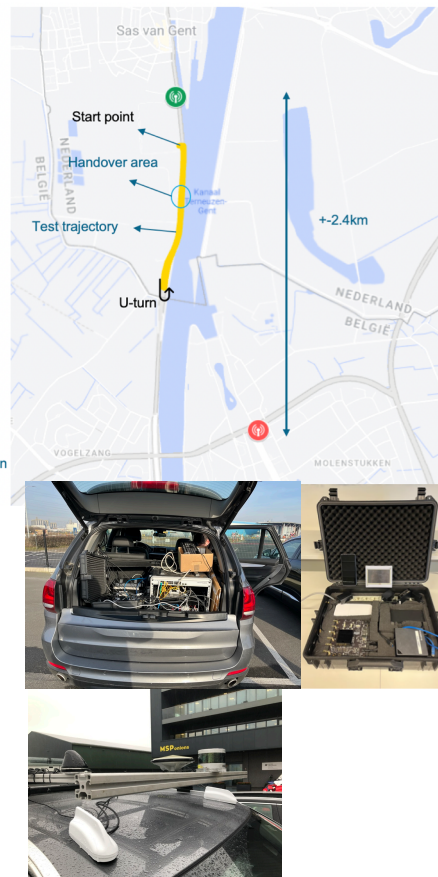
- N2 handover: 100-120ms
- N14 handover: 100-150ms

## Field results

- Uplink throughput: 32.4 Mbps
- Downlink throughput: 145 Mbps

- N14 handover: ~100ms
- Latency between the two cores: ~7ms → small impact compared to the other latency components

 KPN SA base station  
 Telenet SA base station



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# Summary

## Teleoperation of vehicles

- Autodocking successfully tested with the full-scale trucks over 5G SA
- Teleoperation of vehicles (Toyota vehicles and DAF trucks) successfully tested over 5G SA in the national sites (BE, NL)
- Network testing demonstrated that its performance enables **safe teleoperation across borders**
- Testing campaigns with teleoperation of vehicles ongoing in the cross-border setup

## Seamless roaming

- 5G-Blueprint solution one of the first practical implementations for seamless roaming in 5G SA
- Solution combines Home routed SA roaming with the N14 interface
- Service interruption time significantly reduced → sufficient for teleoperation (<150ms)

# Lessons learned

## Teleoperation of vehicles

- Human factors need to be considered for teleoperation: varying driver experiences, resolutions and frame rate effects, fatigue
- Handover-caused interruption times sufficient for cross-border teleoperation

## Seamless roaming

- Standardization potential:
  - New procedure to enable Home-Routed Seamless roaming in 5G SA → **merges** N14 handover with Home-Routed Roaming
  - Seamless roaming with inter-PLMN handover in **both** directions → procedure for V-PLMN to H-PLMN direction is also missing in standards.
- Handover decisions currently based on signal strength, exploring other criteria (allowed IMSI, service availability, contractual relations)
- Vast amount of configuration parameters → to be automated

# Join us at the final event



**Date:** November 21st 2023

**Location:** [Industrial Museum Zeeland](#), Sas van Gent, The Netherlands

The event is free of charge, but registration is mandatory, due to limited seats