





INTRODUCTION TO 5G-BLUEPRINT

Wim Vandenberghe, I&W

KPN event "The role of 5G", April 5th 2022, Helmond

5G-BLUEPRINT IN A NUTSHELL





TELEOPERATED TRANSPORT







Fast

Reliable

Secure

Guaranteed

Cross-border



CHALLENGES



ECONOMICS

- Reduction of waiting time
- Reduction labour shortage
- Economic growth

- Safer driving
- Facilitator automated mobility
- Complex business model

GOVERNANCE

- MNO SLA's
- ToD service SLA's
- Legislation

- Certification
- Liability
- Data sharing and GDPR

5G-BLUEPRINT ULTIMATE GOALGOAL OF THE PROJECT



5G-Blueprint designs and validates technical architecture, business, and governance model for uninterrupted cross-border teleoperated transport based on 5G connectivity.



TECHNOLOGICAL



BUSINESS



REGULATORY

OBJECTIVES



ECHNOLOGICAL

- Design and implement a 5G networkfor CAM services
- Develop and implement the prototype of a TO system
- Implement and deploy enabling functions guaranteeing safety and increasing value
- Validate the end-to-end TO transport solution supported by 5G in real-life crossborder scenarios

BUSINESS



- 5G TO transport market analysis
- Commercial possibilities
- Positions the possible role of TO transport based on 5G in CAM
- TO transport based on 5G connectivity market adoption

REGULATORY



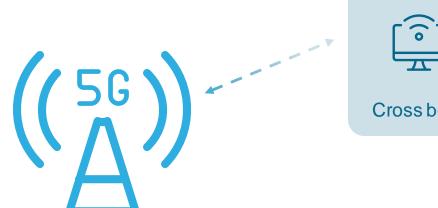
- Identify regulatory issues
- Recommended actions

USE CASES



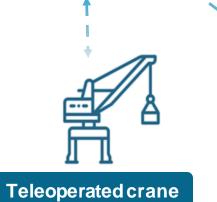
UC1: Automated barge control





UC2: Automated driver in loop docking





UC4: Remote take over

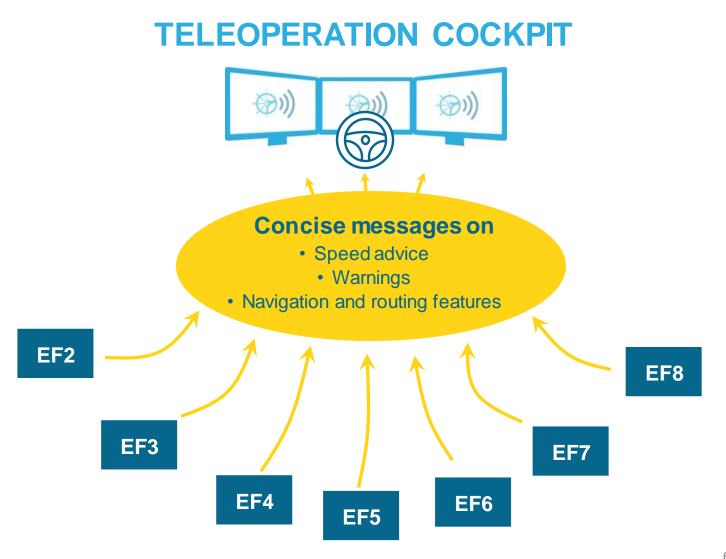


UC3: CACC based platooning





EF1	Enhanced awareness dashboard
EF2	Vulnerable Road User (VRU) interaction
EF3	Timeslot reservation at intersections
EF4	Distributed perception
EF5	Active collision avoidance
EF6	Container ID recognition
EF7	ETA sharing
EF8	Scene Analytics



PILOT AREA



VLISSINGEN SITE

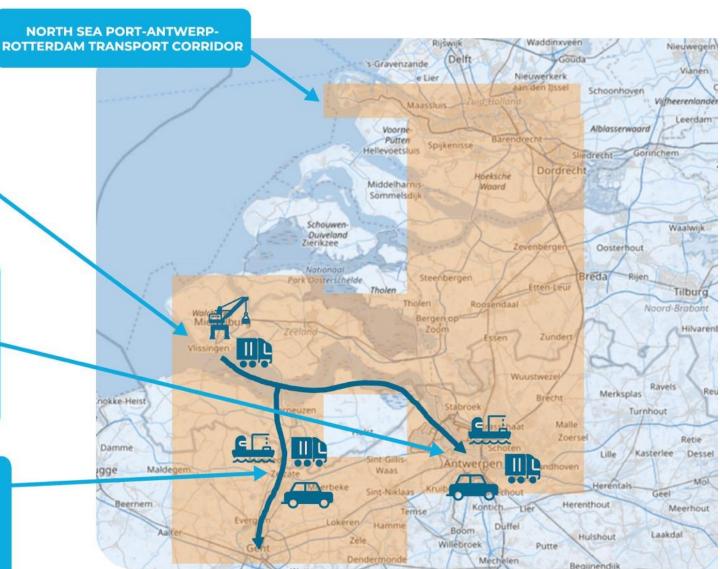
- Teleoperation
- Gracefully degrading safety fallback
- Teleoperation station for operator
- Cameras at terminal
- Docking service
- Logistics chain optimization

PORT OF ANTWERP SITE

- Teleoperation
- Gracefully degrading safety fallback
- Teleoperation station for operator
- Cameras at terminal
- Cooperative Adaptive Cruise Control (CACC)
- Logistics chain optimization

ZELZATE CROSS-BORDER SITE

- Teleoperation
- Gracefully degrading safety fallback
- Teleoperation station for operator
- Cooperative Adaptive Cruise Control (CACC)



PROPOSED SCENARIO DISTRIBUTION ACROSS SITES



Use-case	Vlissingen	Zelzate	Antwerp
UC1 Automated Barge Control		 Cross-border passive Navigating canal with obstacle (bridge) at the border location 	"Hard" conditionsNavigating busy port
UC2 Automated driver-in-loop docking	Full use case 2 4 5 6 7 • Truck docking • Crane operation		no test/demo only deployment
UC3 CACC based Platooning	 Milk run Between terminal and MSP factory (same trajectory as UC4) 1 2 3 4 5 7 	 Cross-border (tentative) PC5 Mode 3 or UU CACC handover (tentative) 1 2 3 4 5 7 	 Full use case Platooning on different road types Co-existence with ITS-G5 signals
UC4 Remote Takeover Operation	 Terminal traffic & basic milk runs Confined area (terminal) Short route over 50 km/h public roads and with limited traffic between terminal and MSP factory 	 Cross-border, high speed, urban Crossing the border on 50 km/h public road, 90 km/h in Flanders Urban environment with presence of iTLCs 1 2 3 4 5 7 	Milk runs • Short route over 50 km/h public roads, including 2 parallel locks, between terminal and Transport Roosens

Enabling functions:



Enhanced awareness HMI



Time slot reservation intersection

Distributed perception



Active collision avoidance





ETA sharing



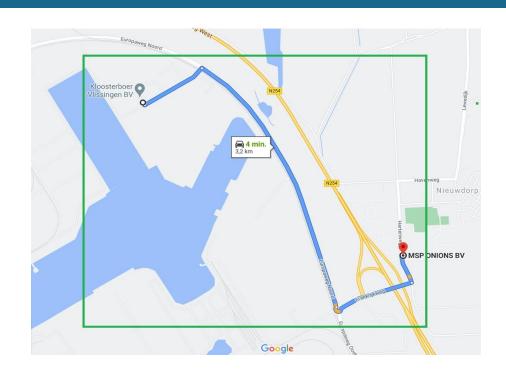
VLISSINGEN SITE DETAILS

https://www.google.be/maps/@51.4581162,3.6968918,13.75z



VLISSINGEN DETAILS







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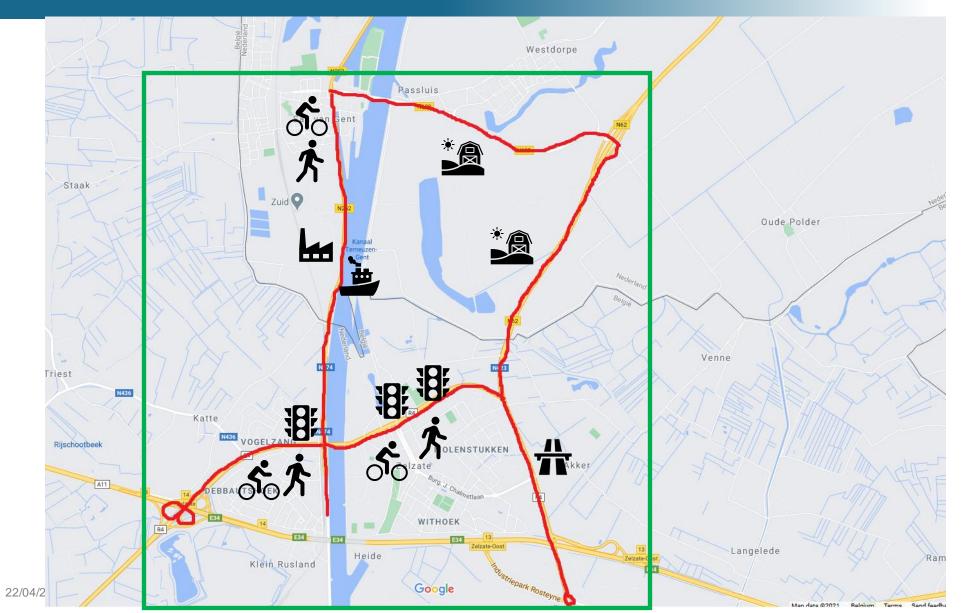
ZELZATE SITE DETAILS

https://www.google.be/maps/@51.207446,3.8004474,15.25z



ZELZATE DETAILS







ANTWERP SITE DETAILS

https://www.google.be/maps/@51.2894393,4.2511426,13.5z





ANTWERP DETAILS



Container pickup /

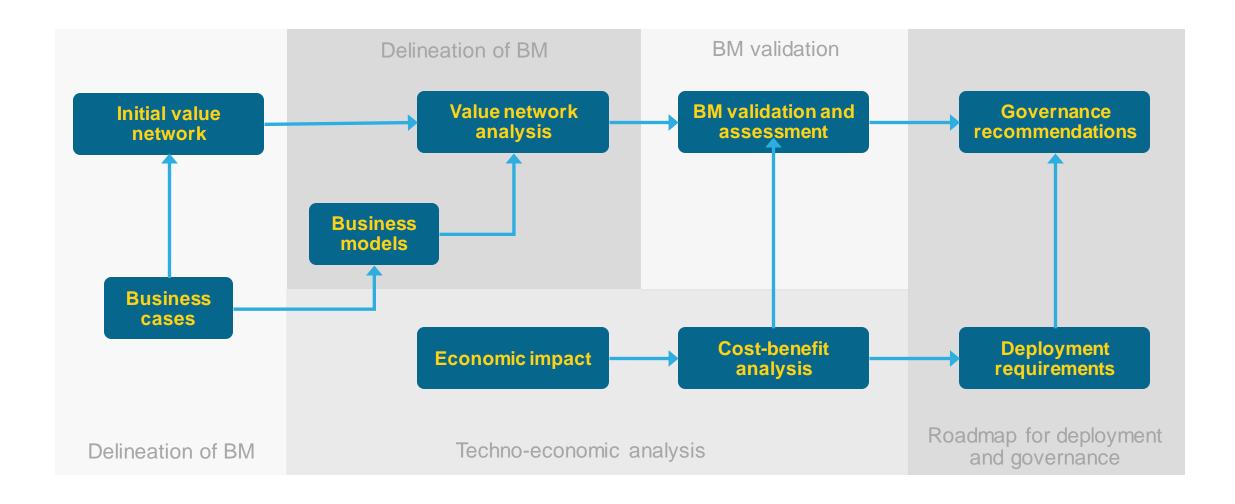
drop-off point (using reach stacker



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CAM GOVERNANCE AND BUSINESS MODELS





CONSORTIUM AS A WHOLE



Network operators







Vehicle OEMs



Teleoperation OEMs









Logistics
Transport













Software

[sentors]

room 40



Connected Mobility sector







Research institutes







Business accelerator











CONSORTIUM ADVISORY BOARD









FACTS & FIGURES



Project Acronym: 5G-Blueprint

Project Name: Next generation connectivity for enhanced, safe & efficient transport & logistics

Funded Under: H2020-ICT-2018-20

Topic: ICT-53-2020: 5G PPP (5G for Connected and

Automated Mobility)

Call for proposal: H2020-ICT-2019-3

Starting Date: 01/09/2020

Duration: 36 Months

Total cost: EUR 13,9 M

EU contribution: EUR 10 M

Project Coordinator: Dr Wim Vandenberghe, Ministerie van Infrastructuur en Waterstaat

Technical Coordinator: Prof. Johann Márquez-Barja, Interuniversitair Micro-Electronica Centrum

CONCLUSION



- 5G-Blueprint is
 - Tackling challenging teleoperation-related use cases
 - Exploring the capabilities of 5G regarding not only eMBB but also URLLC requirements at the same time
 - Investigates the feasibility of teleoperation over 5G in the context of transport and logistics from a technical, business and governance perspective
 - Aiming to deliver the roadmap to enable future deployments in Europe
 - Performing its first pilot activities in June 2022, so stay tuned!

BACK UP SLIDES

MAIN ACTIVITIES, MILESTONES, DELIVERABLES

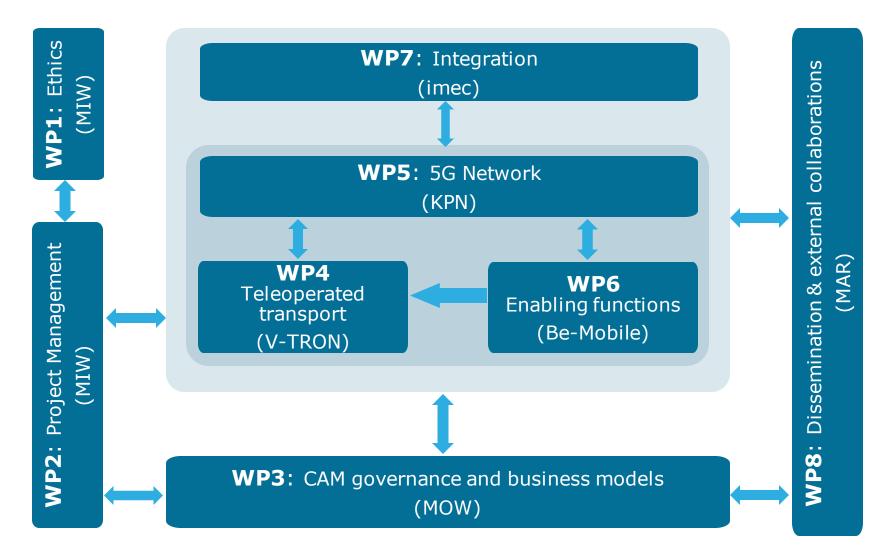


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			20	20							20	21											20	22									20	23			
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		PM1	PM2	РМЗ	PM4	PM5	PM6	PM7	PM8	PM9	PM10	PM11	PM12	PM13	PM14	PM15	PM16	PM17	PM18	PM19	PM20	PM21	PM22	PM23	PM24	PM25	PM26	PM27	PM28	PM29	PM30	PM31	PM32	PM33	PM34	PM35	РМ36
WP1	Ethics																																				- 3
	Ethics requirements						D1.1 D1.	2																													
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T2.1	Project coordination and		-	D2.1										-											-												
	Technical management		1														1															1					125
	Quality assurance and risk						D2.2												D2.3						1							9				1	D2.4
WP3	Governance and business models	MS03																															MS03				MS04
	Description of business cases	1								D3.1															-												
	Delineation of business models																		D3.2		9 0							1 1							3 3		- 6
	Techno-economic analysis																		DUIL								D3.3										
	Business model validation																										50.0						D3.4				
	Roadmap for deployment and																											-				-	50,4				D3.5
	Teleoperated transport		100			li i				0 1							0							-01								1		MS05	3		MS06
	Defining use case requirements																																	MIGUS			MOOO
	System integration for U.C. 2.1		-																		-																_
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	U.C. 2.3 Lab testing						_							-																							-
	Vision based localization system		_																		1																
	Development of driver-in-loop													-																							
	CACC enabled car and container	_	_																												24.0						
	Integration of teleoperable crane for												-		_						- 1							1			D4.3						- 3
	Teleoperation capabilility integration									2				_																							-
	System evaluation		_				-																								D4.1 D4.2						
	Use case demonstrations		-				_														(****	3			-						
	5G Network												MS07						MS08		MS09						MS10				MS11	1					MS 12
	Definition of the network												D5.1																								
	Planning, implementation and																						D5.2														
	Governance between MNOs at																											()			D5.3						D5.8
	Test plan and evaluation of the 5G																														D5.4						
	Hybrid 5G C-V2X communication																																				5.5-D5.6
	Study on the use of public/private															D5.7	1	1										1				3			1		
	Enabling functions	7											()	()							\$ N				4 2									MS13	1	-	100
	Description of enabling functions			D6.1																																	
T6.2	Architecture						D6.2			D6.3				1							1							1									
T6.3	Function development	Č-	4			11 1							1	7			1							-	-			7			4	9			1	-	- 5
	Front end development					2																		7								-			0		
	Deployment and operation																																				
	Evaluation					9 3				-				9							1			1				1									D6.4
	Integration		8			1/2							MS14								()				MS15						MS16	2			-		MS17
	Requirements and Architecture												D7.1																		D7.3						
	System Integration of Teleoperated																								D7.2												17
	Development of Minimum Viable 5G-		-			1				2				-																		-			1		N 1
	Final Evaluation and Demonstration																											,									D7.4
		MS18											MS19												MS24												MS21
	Dissemination and communication		D8.2	D8.1						D8.5				8					D8.3																- 3		D8.4-D8.6
	Joint events and community building		DU.2	50.7						20.0				1					50.0		9			2 33													J. T-100.0
	Standardisation																																				-
	Project exploitation												-	-																							
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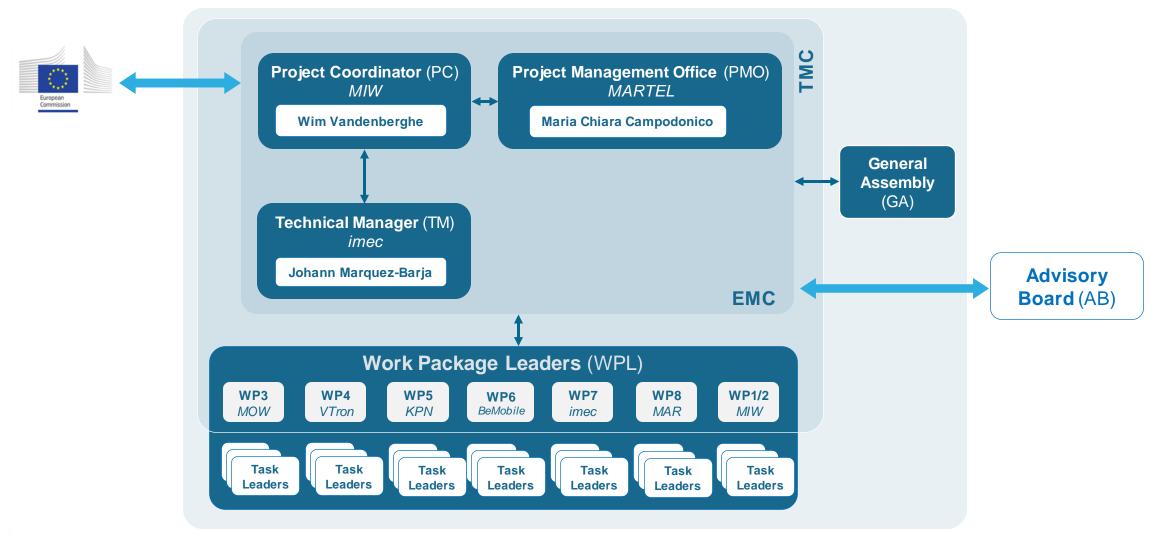
WP STRUCTURE





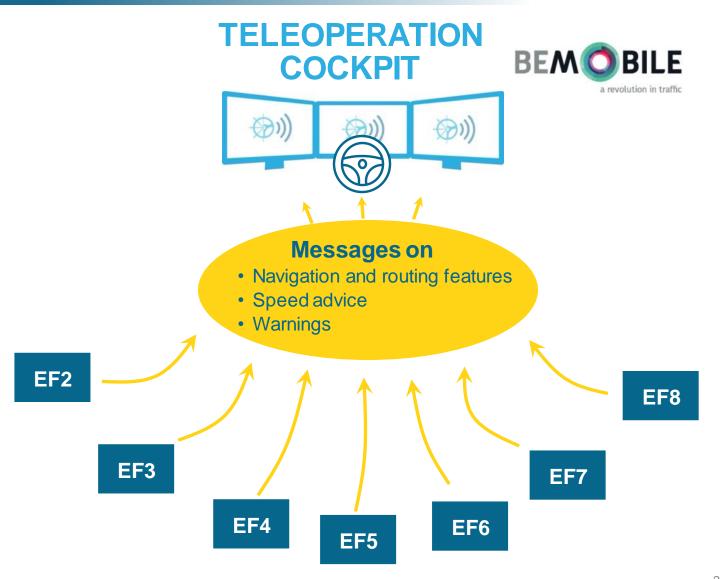
GOVERNANCE





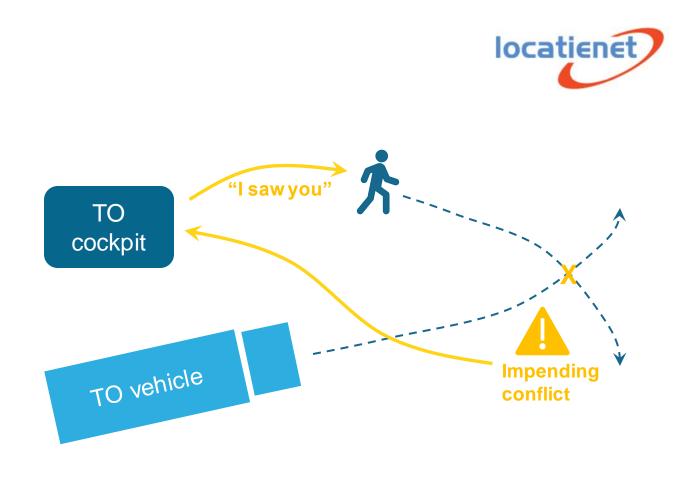


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EF2	Vulnerable Road User (VRU) interaction
EF3	Timeslot reservation at intersections
EF4	Distributed perception
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EF7	ETA sharing
EF8	Logistics chain optimization



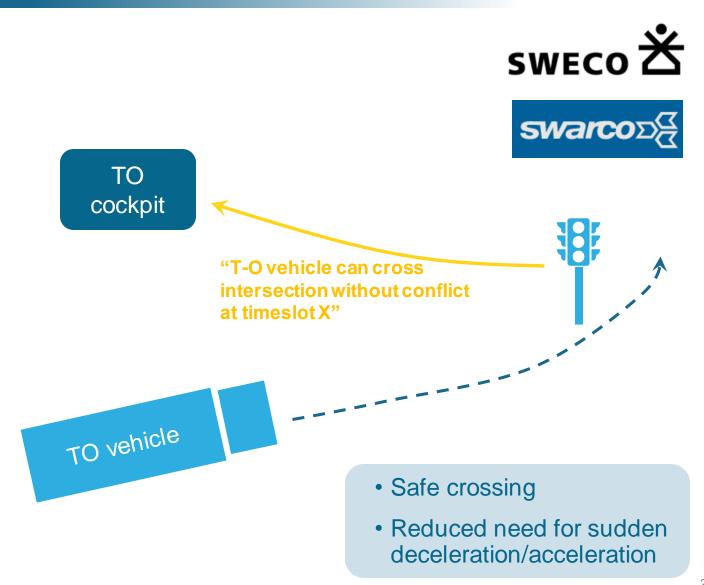


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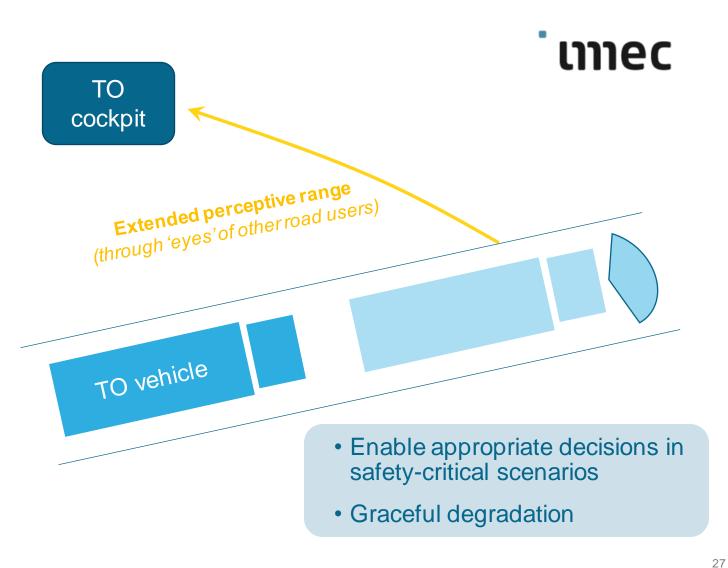


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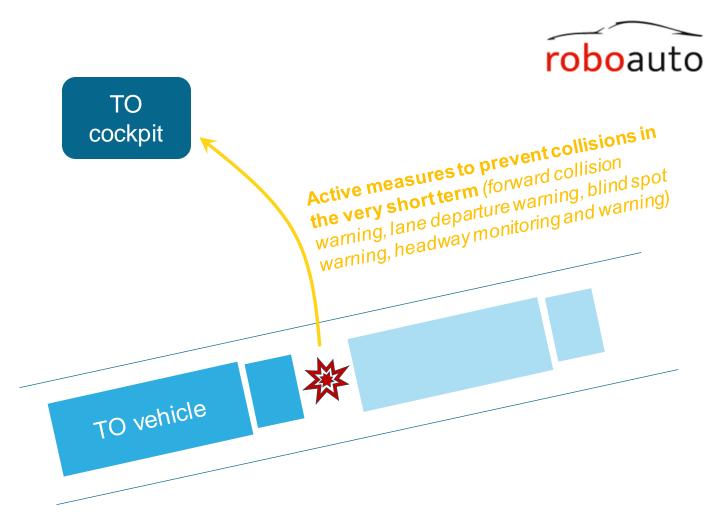


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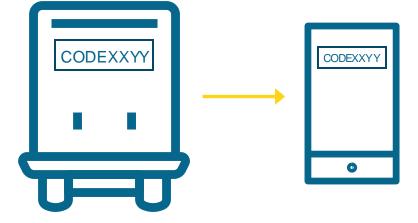
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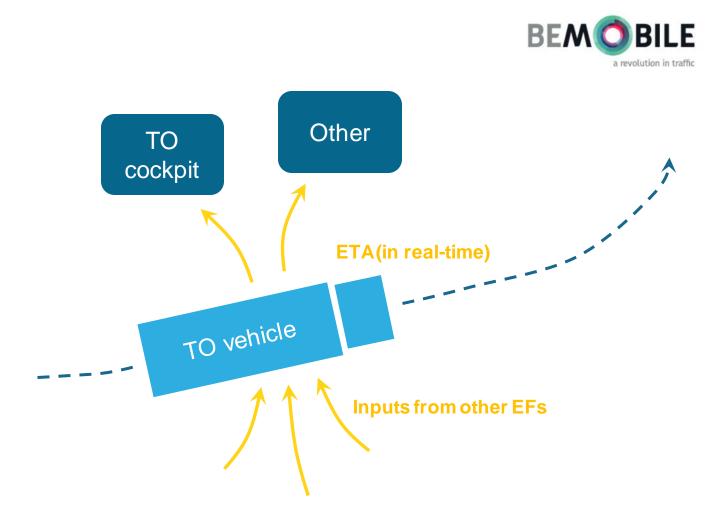
Plug&Play, Deploy Anywhere system on 5G network

Potential use-cases:

- Exit/entry detection in ports
- Detection of dangerous goods transport
- Truck platoon order monitoring

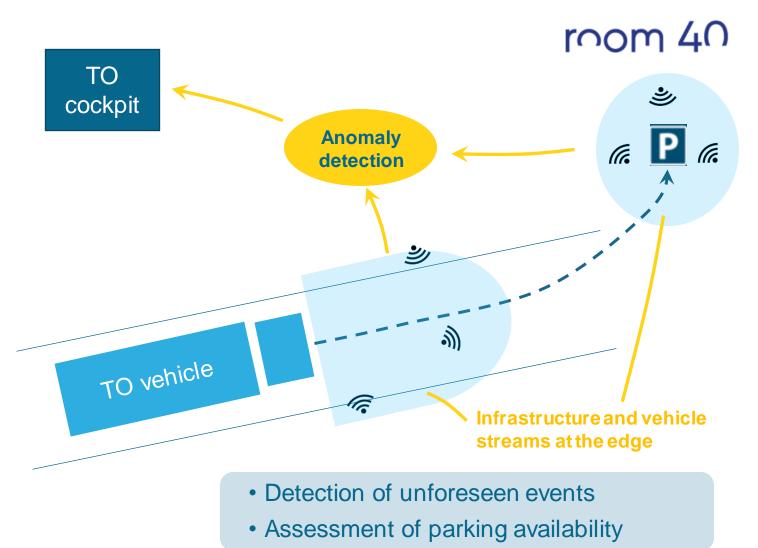


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THANK YOU FOR YOUR ATTENTION







